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Ref: K. Ogata, Modern Control Engineering

Lecture #24 Linear Quadratic Regulator (Nov 17, 2011) Ref: K Ogata, Modern Control Engineering 2002 Given a system in state-space form: $\dot{x} = Ax + Bu$ $y = Cx$ (1)

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Katsuhiko Ogata, "Discrete-Time Control Systems", "Modern Control Design with MATLAB and SIMULINK", John Wiley & Sons, Ltd, 2003 Grading Policy Sessional Marks: 70 (assignments, attendance, and two written tests) Digital Control Systems (EE680) Dr K m Hasan MSc Electrical Engineering Spring-2009 L e c t u r e S c h e d u l e

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